

**EUROPEAN PATENT APPLICATION**

Application number: 85113331.4

Int. Cl.<sup>4</sup>: G 02 B 7/00

Date of filing: 21.10.85

Priority: 22.10.84 US 563307

Date of publication of application:  
30.04.86 Bulletin 86/18

Designated Contracting States:  
DE FR GB IT SE

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Multi-degree of freedom mount.

The specification discloses a mount for an optical device having rotational and translation freedom, in particular 6 degrees of freedom in three translations along x, y and z axes and three pivotal or rotational movements about each of the axes. The mount is particularly useful in mounting scanning cameras, robotic eyes, or correlating image or pattern recognition devices for use in self-guided missiles. When used in free-flight, the three pivotal or rotational movements correspond to pitch, roll, and yaw. A semi-spherical drive means (11, 12) which is rotatably journaled in a complimentary semi-spherical fixed mount. The drive means (11, 12) defines an optical axis within having interior threads. A first carrier (13) is threaded into the drive means (11, 12) and translated along the z axis by rotation of the spherical drive means (11, 12). A second carrier is mounted for x, y translation within the first carrier (13). Pivotal or rotational movement about the x and y axes may occur between the first carrier (13) of the drive hemisphere, or between the drive hemisphere and the fixed mount (14). Roll movement about the z axis occurs between the first carrier (13) and the fixed mount (14).

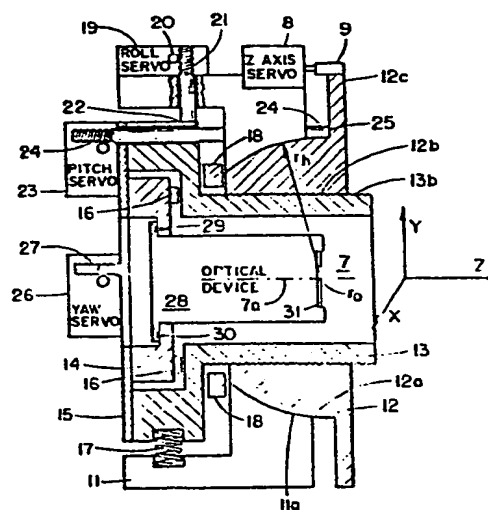


FIG.2

October 21, 1985 0179426

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MULTI-DEGREE OF FREEDOM MOUNT

The present invention is a mount for an optical device having six degrees of freedom and is intended for use in optical systems such as an optical correlator, a scanning television camera, a robotic eye, or optical bench systems involving mirrors, lenses, or light sources such as lasers or other optical components.

10           The prior art devices used for supporting and centering optical components generally provide separate means for translating the component along the x, y and z axis, and for pivoting the component about the x and y axis. While these devices are suitable for use in  
15           optical bench systems, where space is not at a premium, they are generally unsuitable for military or industrial applications wherein a plurality of optical components must be closely fitted together in a closely defined relationship.

20           For example, U.S. Patent 3,511,462 entitled "Device for the Supporting and Centering of Components" discloses an optical bench mount having a set of gimbals to provide for pivotal movement, and three separate carriages to provide for translation along the  
25           x, y and z axis. This device provides for 5 degrees of movement, three translations, and two angular pivots.

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1 U.S. Patent 4,099,852 discloses a "Lens  
Positioner With 5 Degrees Of Freedom" which also  
provides for three translations and two angular  
rotations. This device uses five micrometer heads or  
5 motorized linear actuators to translate a lens about  
three axis, and two angular rotations.

U.S. Patent 4,088,396 discloses an "Optical  
Mount With Independently Orthogonally Adjustable  
Element" which provides for 2 degrees of rotational  
10 freedom about orthogonal axis by means of a  
semi-spherical mount, and a pair of adjusting screws  
which pivot the semi-spherical component with respect  
to the base. This reference also discloses screw  
threads and an internal optical passageway within the  
15 semi-spherical mount. The reference does not disclose  
the use of these screw threads for translation along a  
z axis.

Danish patents 63 545 entitled  
"Vinkelindstillelig Objektivfatning" also uses  
20 semi-spherical mounts and orthogonally located  
adjusting screws for pivoting one of the semi-spherical  
components with respect to the other to thereby provide  
rotational pivots about an optical axis.

This reference also discloses the use of  
25 external screw threads for adjusting the tension  
between these semi-spherical elements, but does not  
disclose the use of screw threads for positioning any  
optical component along a z axis.

U.S. Patents 3,588,230 entitled "Adjustable  
30 Lens Mount" and 4,408,830 entitled "Multi-Directional  
Translator Mechanism" disclose mechanisms which provide

1 translation along an x and a y axis for optical  
components such as mirrors, lenses, prisms, and the  
like. U.S. Patent 4,408,830 also discloses a carrier  
which is resiliently biased to a predetermined position  
5 by means of adjusting screws.

U.S. Patent 3,204,471 entitled "Angle  
Adjusting Mechanism For Optical Elements" and U.S.  
Patent 3,588,232 entitled "Precision Adjustable  
Assembly For An Optical Bench Mark" disclose gimbal  
10 devices that may be fixably positioned for pivotable  
movement about an axis by means of adjustable  
stud screws. U.S. Patent 3,204,471 is resiliently  
biased to a predetermined position by a combination of  
the torsion springs and the adjusting screws.

15 U.S. Patent 3,642,353 discloses an optical  
mirror assembly which is positioned by means of  
semi-spherical bearing surfaces and retained in  
position by means of a wave spring. The mirror may be  
pivoted about x and y axis by means of a set of  
20 adjusting screws which pivots the mirror assembly.

None of the foregoing devices are able to  
provide translation in all three axis, and rotation  
about each of the axis to provide 6 degrees of freedom  
or movement in the mount.

25 Traditionally, any device capable of  
translation in each of the x, y and z axis requires a  
minimum of three moving parts, and a gimbal or similar  
device providing 2 degrees of pivotal or rotational  
freedom about two axis also requires three moving  
30 parts. The present invention will provide 4 degrees of  
motion with three component parts, and 6 degrees of  
motion with four moving parts.

1           The present invention provides an optical  
mount having rotational and translation freedom comprising  
first and second semi-spherical support means adapted  
for rotational movement therebetween, the first support  
5 defining a z rotational axis and a pivot point within,  
the first support also defining a threaded opening which  
surrounds said rotational axis and said pivot point. The  
optical mount includes a first carrier having an exterior  
thread which engages the threaded opening and translates  
10 the carrier along the z rotational axis in response to  
rotation of the first semi-spherical support means, the  
first carrier defining an optical opening therein. A  
mounting means is mounted within the first carrier, the  
mounting means defining a support within the optical opening  
15 for an optical means. The optical mount also includes an  
adjustable means for pivoting the first carrier about the  
pivot point.

          In one embodiment, the present invention is a  
precision mount for optical use having 6 degrees of freedom,  
20 translation along three orthogonal axis x, y and z, and  
rotation about each axis. A base mount is provided  
with a spherically contoured receiving surface into  
which is journaled or fitted a mating drive means which  
rotates within the receiving surface. The drive means  
25 defines an internally threaded screw thread which  
surrounds an optical passageway. A first carrier  
having external screw threads engages the internal  
screw threads of the spherically contoured drive means  
and is translated along the optical axis or the z axis  
30 in response to rotation of the spherical drive means or  
other means to achieve translation along "z" axis. The  
second carrier is mounted within the first carrier to

1 provide for translation along the x and y axis within  
the first carrier. Rotational movement about each of  
the axis may be provided between the first carrier and  
the semi-spherical drive means, or in the alternative,  
5 rotation about the x and y axis may be provided by  
pivoting a semi-spherical drive means within the  
semi-spherical receiving surface. In either case,  
rotational movement about the z axis is provided by  
rotating the first carrier with respect to the  
10 semi-spherical drive means.

An optical means is mounted on the second  
carrier. If desired, the optical means may be extended  
forwardly within the optical passageway to the pivot  
point or radius of the semi-spherical surface. At this  
15 location, the optical means may be rotated about each  
of the three axis, with zero linear movement because  
the light beam of the optical means is allowed to go  
through the center of the mount. Any optical component  
can thereby be mounted at the center of rotation for  
20 each of the three optical axis. If desired, the  
optical component can then be translated along the x, y  
or z axis as desired.

Because of the manner in which the device is  
constructed, the invention provides a multi-degree of  
25 freedom mount for optical components that require  
adjustment and occupy a minimum amount of space. The  
invention is particularly useful for active optical  
components such as robotic eyes, target seeking  
missiles, scanning television cameras and moving  
30 reflectors. The device is also applicable to any  
optical system which requires or needs multi-degree of

1 freedom adjustment. This includes optical bench  
systems using prisms, lenses, mirrors or light sources  
such as laser beams. The device is also particularly  
useful for use in one or more optical correlators used  
5 in pattern recognition systems.

In addition, by adding several drive motors,  
the device can be used in an active optical system used  
to match and identify parts, shapes, structures,  
terrain and targets.

10 The device is unique in that three components  
of the mount utilizing the threaded spherically  
contoured drive and mount can result in 3 degrees of  
motion while using a minimum of space. The mount can  
tilt or pivot the optical device about each of the x  
15 and y axis for scanning purposes, while simultaneously  
translating the optical component along the z axis to  
provide focusing ability in an active optical system.  
This device also has the unique feature that the center  
of rotation can be arbitrarily chosen or varied by  
20 changing the radius of curvature of the spherically  
contoured surfaces.

In a second embodiment, a first and second  
spherically contoured support means are adapted for  
rotational movement therebetween. The first support  
25 also defines a threaded opening therein which surrounds  
a z rotational axis and the pivot point. A first  
carrier having threads thereon engages the threaded  
opening and translate the carrier along the z  
rotational axis in response to rotation of the first  
30 spherically contoured support means. The first carrier  
defines an optical opening therein. The second carrier

1 may be mounted within the first carrier with the second  
carrier also defining a support within the optical  
opening for an optical means. An x and a y translation  
means for translating the second carrier with respect  
5 to the first carrier along an z and a y axis is  
provided. In addition, adjustable means are provided  
for pivoting the first carrier about the pivot point to  
thereby rotate the first and second carrier about each  
of the x and y axis. Rotation about the z axis is  
10 provided by rotating the first carrier with respect to  
the first semi-spherical support means. As indicated  
previously, the adjustable means which provides  
rotation about the x and y axis may accomplish this  
result by pivoting the first spherically contoured  
15 support means with respect to the second, or by tilting  
the first carrier with respect to the first  
spherically contoured support means.

In one embodiment of the invention, the first  
and second carrier are resiliently mounted in a biased  
20 or predetermined position by adjustment screws. In an  
alternate embodiment of the present invention, the  
adjustment screws are rotated by servomotors which  
provide positive displacement of the respective  
component parts in response to rotation of the  
25 servomotors. Additionally, linear stepping motors could  
be provided to effect the relative positioning of the  
parts. The device is particularly useful for  
positioning a photosensitive optical device such as a  
television camera or a charge coupled device. In  
30 addition, the device may be used to correlate or  
position a mirror, lens, or laser beam as desired, or

1 two or more devices may be used to align a correlator,  
with its holographic fourier transform lens and its  
array of matched filters.

In accordance with the accompanying drawings,  
5 Figure 1 is a sketch illustrating the x, y and z orthogonal  
axes, and the yaw, pitch, and roll movements about each  
of the axes that will be used in explaining the operation  
of the mount.

Figure 2 is a partial cross-section of one  
10 embodiment of the present invention illustrating a section  
of the device along the y and z axis.

Figure 3 is an isometric and diagrammatic  
view of a second embodiment of the present invention  
illustrating the translation along each of the axis, and  
15 the pitch, yaw, and roll adjusting screws.

Figure 4 is a rear plan view of still another  
embodiment of the present invention illustrating x and  
y translation adjustments, the roll adjustment, and the  
location of the pitch and yaw adjust screws.

20 Figure 5 is a partial cross-section side view  
of the device illustrated in Figure 4 illustrating the  
translation along the z axis and the pitch and yaw  
adjustment screws.

As illustrated in Figure 1, the present  
25 invention provides translation along each of the x, y  
and z axis, and rotation about each of these axis to  
provide pitch, yaw and roll adjustment. Each of the x  
y and z axis are generally orthogonal to each other,  
and the device normally provides 3 degrees of rotational  
30 movement. The translation adjustment and the degree of  
rotation of freedom is governed by the relative sizing and  
spacing of the components, and as will hereinafter be  
described, can be assembled with a wide variety of spacing  
adjustments.

1           As illustrated in Figure 2, one embodiment of  
the invention is illustrated in a cross sectioned  
elevation sideview along a plane defined by the y and z  
axis.

5           As illustrated in Figure 2, a base member 11  
is provided for mounting the mount to a fixed surface.  
Base member 11 defines a spherically contoured  
receiving surface 11a which receives a spherically  
10           contoured drive means 12 mounted within the receiving  
surface. The spherically contoured drive means defines  
an internal screw thread 12a. A first carrier 13  
having external screw threads 13b threadably engages  
the semi-spherical drive means 12 for translation of  
the first carrier 13 along the z axis as illustrated in  
15           Figure 2. The spherically contoured drive means 12 may  
be rotated by means of the z axis servo 8 which rotates  
a drive roller 9 which engages the outer drive flange  
12c of the spherically contoured drive means. Rotation  
of the y axis servo advances the first carrier 13 along  
20           the z axis by virtue of threads 12b and 13b. A second  
carrier 14 is mounted within the first carrier 13 for  
translation along the x and y axis as will hereinafter  
be more fully described with respect to Figures 3 and  
4. The second carrier is retained within the first  
25           carrier by means of flange 15 and wave spring 16. The  
first drive means is also resiliently mounted by virtue  
of springs 17 and 18 wave spring and biased to  
predetermined positions by means of adjustment screws  
21, 25, and 27. The adjustment screws 21 is rotated  
30           and driven downwardly by means of drive gear 20 and  
roll servo 19 to engage the first carrier as indicated

1 at 22. Likewise, drive screw 24 is driven by pitch  
servo 23 to engage the base member 12<sub>c</sub> as indicated  
at 25. In a similar manner, drive screw 27 is driven  
by yaw servo 26 to also react between (not shown) base  
5 member 11 and 12<sub>c</sub> through clearance hole in 12B.

The mount defines an optical passageway 7 and  
optical axis 7a having a central pivot point  $r_o$  and a  
semi-spherical radius  $r_h$  which define the neutral  
point of the mount. Mounted within the optical  
10 passageway 7 is an optical device 28 which is secured  
to the second carrier 14 by means of screws 29 and 30.  
The optical device is generally representative of any  
photosensitive device, and may be a conventional  
vidicon, or a charge coupled device. The optical  
15 component 31 is normally mounted at  $r_o$  to provide for  
zero linear displacement of the optical component in  
response to rotation about each of the x, y and z axis.

As illustrated in Figure 3, the x and y  
translation adjustment is accomplished by means of  
20 adjusting screws 32 and 33 which translate the second  
carrier 14 with respect to the first carrier 13. The  
second carrier also provides a mounting means for the  
optical device to be mounted. The second carrier 14  
may be resiliently biased into position by means of  
25 springs 34 and 35 and held in a predetermined position  
by means of lead screws 32 and 33. Alternately, wave  
springs such as those illustrated at 16 in Figures 2  
and at 16 and 25 in Figure 5 may be used. Rotation of  
the lead screw 32 results in translation of the second  
30 carrier 14 along the x-x' axis. Likewise, rotation of  
the lead screw 33 results in translation of the second

1 carrier along the y-y' axis. As was previously  
indicated with respect to Figure 2, rotation of the  
semi-spherical drive means 12 results in translation of  
the first carrier, and consequently the second carrier,  
5 along the z axis.

Rotation about each of the axis is  
accomplished in the embodiment illustrated in Figure 3  
by displacing the first carrier 13 with respect to the  
base member 11. Rotation about the z axis (roll) is  
10 accomplished by advancing lead screw 21a downwardly  
into engagement with the first carrier 13 as indicated  
at 22a. The first carrier 13 is resiliently biased  
downwardly on the opposite side of center by means of  
spring 17a. Center, as the term is used in Figure 3,  
15 would refer to the center of rotation of the screw  
threads 12b, 13b (illustrated in Figure 2). As lead  
screw 21a is advanced, it rotates the first carrier 13  
in the direction indicated by the arrow c (roll) about  
the z axis.

20 Likewise, lead screw 27a is advanced inwardly  
to engage the support base 11 as indicated at 25a to  
provide yaw adjustment about the y axis. A spring such  
as 37, which is similar to the spring 17b illustrated  
in Figure 4, or a wave spring (such as spring 25  
25 illustrated in Figure 5) may be used to resiliently  
bias the first carrier 13 and lead screw 27a into  
engagement with the base member 11.

Likewise, lead screw 24a also engages base  
member 11 (not shown) to provide pitch adjustment about  
30 the x axis as illustrated in Figure 3.

1           An alternate embodiment of the invention is  
illustrated in Figures 4 and 5. In this embodiment,  
the yaw and pitch adjustment is achieved by displacing  
semi-spherical drive means 12 with respect to the base  
5 member 11. The lead screw 24a threadably engages the  
base member 11 as indicated in 11e to bias the  
semi-spherical drive member 12 outwardly and thereby  
achieve rotation about the x axis (pitch). Likewise,  
lead screw 27a (illustrated only in Figure 4)  
10 threadably engages the base member 11 (not shown) to  
engage the semi-spherical drive member 12 at a point  
90 degrees from the pitch adjustment screw 24a. By  
adjustment of lead screws 24a and 27a, yaw and pitch  
adjustment may be made about the semi-spherical  
15 surfaces 12a and 12b. Inasmuch as the first carrier 13  
is rotated about the center of rotation  $r_0$  by means  
of lead screw 21b, elongate slots 13d, 13e are provided  
to enable access to the pitch adjustment screw 24a, and  
the yaw adjustment screw 27a. Roll adjustment is  
20 biased by means of a spring loaded member 17b which  
threadably engages base member 11 as indicated in  
Figure 4. In general, cutaways are provided as  
indicated at 11d, 13d, 13e to provide access to the  
adjustment screws where necessary.

25           In the embodiment illustrated in Figures 4  
and 5, a laser diode has been mounted within the  
optical passageway 7 as illustrative of the manner in  
which the mount might be utilized in an optical bench  
device. Laser diode 36 is mounted in the second  
30 carrier 14 by means of screws 29 and 30.

1           As can be seen in Figures 4 and 5, the mount  
provides 6 degrees of freedom in the optical components  
in a configuration that occupies a minimum amount of  
space. As illustrated, the device generally provides  
5 for 3 degrees of rotation about each of the x, y and z  
axis with zero linear movement, but as would be  
apparent to one skilled in the art, the amount of  
rotational movement available is determined by the  
clearance space provided. As indicated in Figure 4,  
10 the size of the clearance space 21 determines the  
amount of x and y translation available. Clearance  
space 22 effectively limits the amount of roll  
adjustment, while the length of the barrel or threaded  
portion of the first carrier 13b effectively limits the  
15 amount of z translation. As illustrated in Figure 5,  
the clearance space 23 and/or 24 effectively limits the  
amount of yaw and pitch adjustment about the x and y  
axis. As indicated in Figure 5, wave springs 16 and 25  
provide a resilient bias for rotational movement by  
20 virtue of the solid coupling between the first carrier  
13 and the semi-spherical drive means 12 by means of  
the threaded connection. The action of lead screw 24a  
is opposed by wave spring 25 acting between base member  
11 and the first carrier 13.

25           The foregoing description of the optical  
mount is intended to illustrate the invention in  
sufficient detail to enable those skilled in the art to  
practice and use the invention. Various modifications  
and alterations may be apparent to those skilled in the  
30 art to adapt the mount to a specific art environments.  
The foregoing description of the various embodiments is  
not intended in anyway to be an exhaustive description  
of the invention, which is to be described and limited  
only in accordance with the following claims:

WE CLAIM:

- 1           1. An optical mount having rotational and translation freedom, said mount comprising:
- 5           a) first (12) and second (11) semi-spherical support means adapted for rotational movement therebetween, said first support defining a z rotational axis and a pivot point within, said first support also defining a threaded opening which surrounds said rotational axis and said pivot point,
- 10           b) a first carrier (13) having an exterior thread which engages said threaded opening and translates said carrier along said z rotational axis in response to rotation of the first semi-spherical support means (12), said first carrier (13) defining an optical opening therein,
- 15           c) a mounting means (14) mounted within said first carrier (13), said mounting means (14) defining a support within said optical opening for an optical means,
- d) adjustable means for pivoting said first carrier about said pivot point.
- 20           2. An optical mount as claimed in Claim 1 wherein said mount further comprises an x and a y translation means, for example x and y drive screws, for translating said mounting means (14) with respect to said first carrier (13) along an x and a y axis.
- 25           3. An optical mount as claimed in Claims 1 or 2 wherein said adjustable means pivots and/or tips said first carrier (13) with respect to said second semi-spherical support means (11) for rotating said first carrier (13) about the x and y axis.
- 30           4. An optical mount as claimed in any one of the preceding claims wherein said adjustable means pivots said first semi-spherical support means (12) with respect to said second semi-spherical support means (11).

- 1           5. An optical mount as claimed in any one of  
the preceding claims in which said adjustable means and  
said translation means and said first semi-spherical  
support means are driven by servomotors.
- 5           6. An optical mount as claimed in any one of  
the preceding claims in which said first carrier (13) and  
said mounting means (14) are resiliently mounted and  
biased to predetermined positions by adjustment screws.
- 10          7. An optical mount as claimed in any one of  
the preceding claims in which said optical means is for  
example a photosensitive device, or a mirror, or a holo-  
graphic lens, or a light source, or a lens.
- 15          8. An optical mount as claimed in Claim 7 in  
which said photosensitive device is a television camera,  
or a charge coupled device.
9. An optical mount as claimed in Claim 7 is  
which said light source is a laser.

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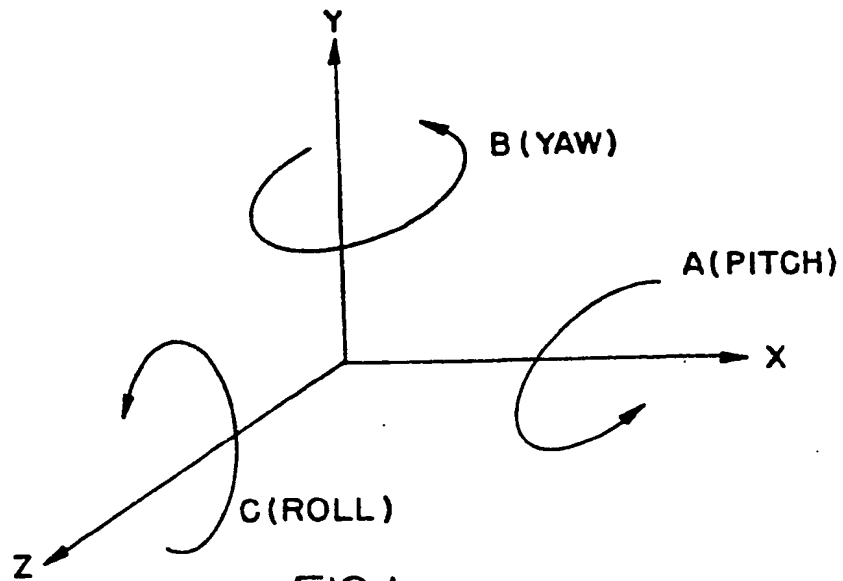


FIG. 1

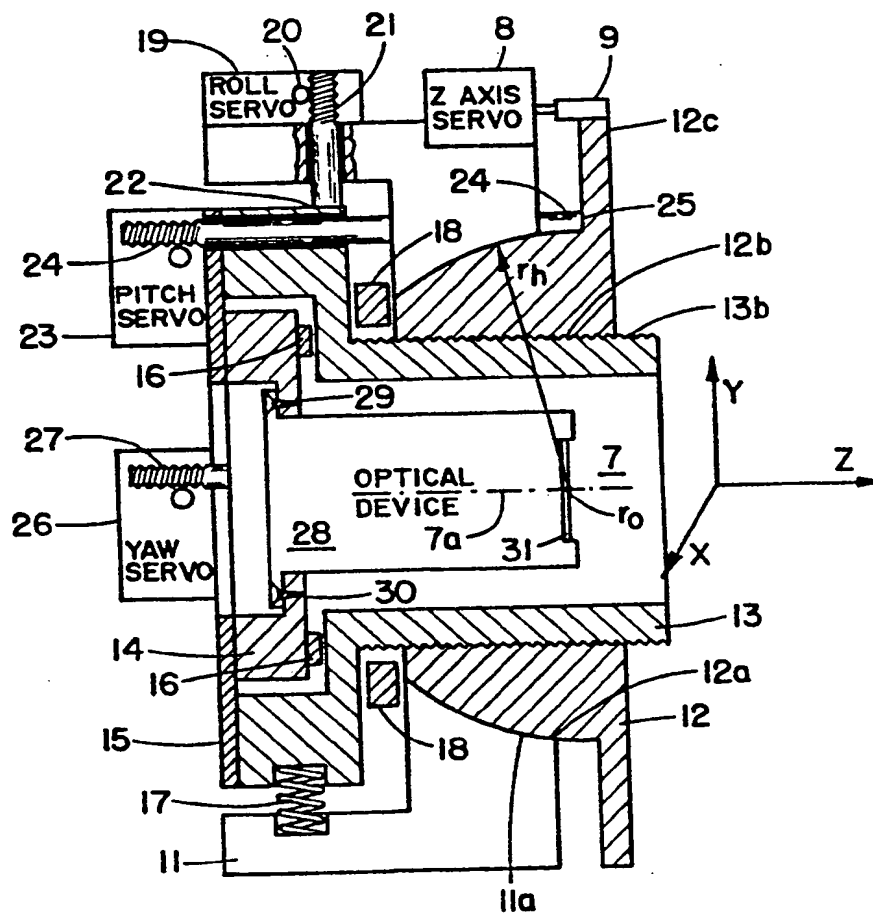


FIG. 2

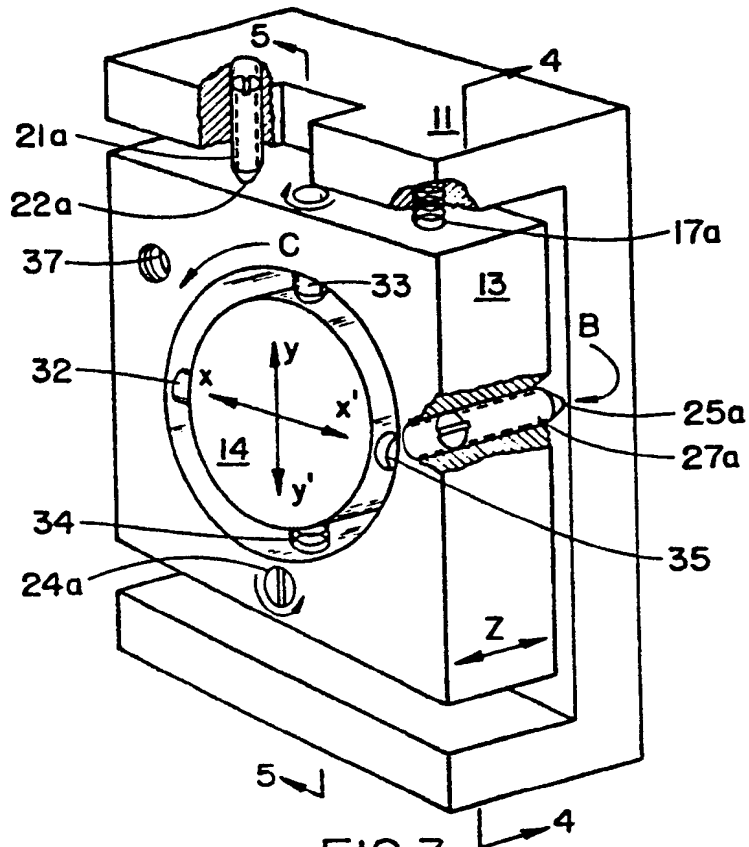


FIG. 3

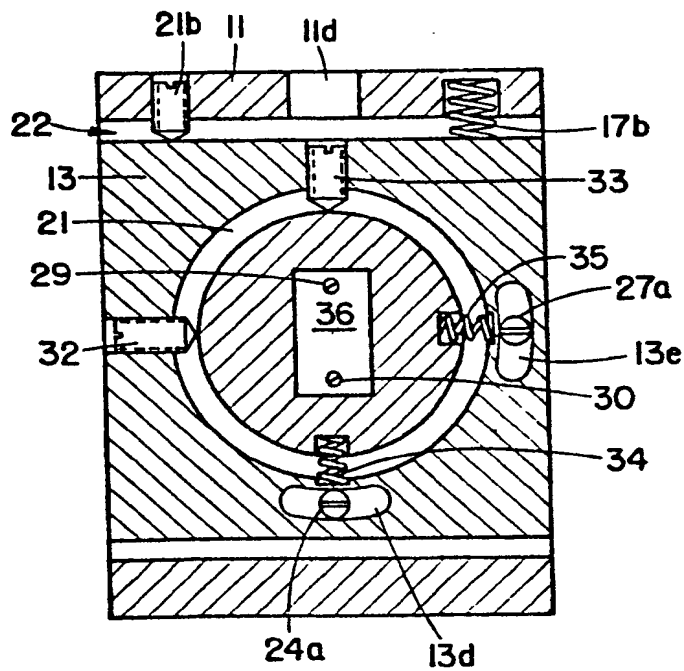


FIG. 4

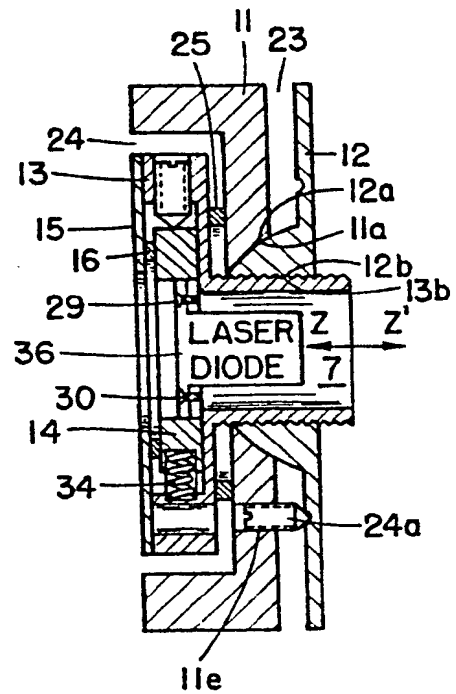


FIG. 5



Europäisches Patentamt  
European Patent Office  
Office européen des brevets

Publication number:

0 179 426  
A3

## EUROPEAN PATENT APPLICATION

Application number: 85113331.4

Int. Cl.<sup>3</sup>: G 02 B 7/00

Date of filing: 21.10.85

Priority: 22.10.84 US 663307

Date of publication of application:  
30.04.86 Bulletin 86/18

Date of deferred publication of search report: 28.10.87

Designated Contracting States:  
DE FR GB IT SE

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### Multi-degree of freedom mount.

The specification discloses a mount for an optical device having rotational and translation freedom, in particular 6 degrees of freedom in three translations along x, y and z axes and three pivotal or rotational movements about each of the axes. The mount is particularly useful in mounting scanning cameras, robotic eyes, or correlating image or pattern recognition devices for use in self-guided missiles. When used in free-flight, the three pivotal or rotational movements correspond to pitch, roll, and yaw. A semi-spherical drive means (11, 12) which is rotatably journaled in a complimentary semi-spherical fixed mount. The drive means (11, 12) defines an optical axis within having interior threads. A first carrier (13) is threaded into the drive means (11, 12) and translated along the z axis by rotation of the spherical drive means (11, 12). A second carrier is mounted for x, y translation within the first carrier (13). Pivotal or rotational movement about the x and y axes may occur between the first carrier (13) of the drive hemisphere, or between the drive hemisphere and the fixed mount (14). Roll movement about the z axis occurs between the first carrier (13) and the fixed mount (14).

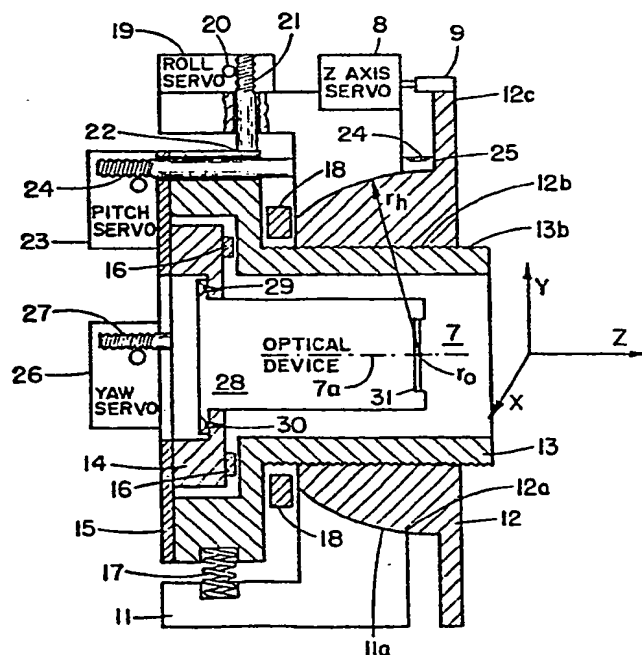


FIG.2

Croydon Printing Company Ltd.



European Patent  
Office

# EUROPEAN SEARCH REPORT

0179426

Application number

EP 85 11 3331

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl. 4)
A,D	US-A-4 088 396 (A. EDELSTEIN) * abstract; figures 1-3; claim 1D *	1,6	G 02 B 7/00
A	--- PATENT ABSTRACTS OF JAPAN, vol. 7, no. 245 (P-233)[1390], 29th October 1983; & JP - A - 58 132 204 (HOYA GLASS) 06-08-1983 * abstract, figures *	1	
A	--- DE-B-2 056 568 (SIEMENS) * claims 1, 2, 9; figures 1-3 *	1-4,6-7	
A,D	--- US-A-4 099 852 (KOBIERECKI et al.) * abstract; figures 4, 5; column 2, lines 17-21; column 4, lines 34-51 *	1,2,5-7	TECHNICAL FIELDS SEARCHED (Int. Cl. 4) G 02 B 7/00
A,D	--- US-A-4 408 830 (WUTHERICH) * abstract; figures 4, 6, 7 *	2,6,9	
A	--- US-A-4 423 850 (BASS) * abstract; figures 3, claim 1 *		
A	--- US-A-3 588 025 (GERSMAN) * abstract; figure 2, claim 1 *		
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The present search report has been drawn up for all claims			
Place of search BERLIN		Date of completion of the search 20-07-1987	Examiner HYLLA W.A.
<p><b>CATEGORY OF CITED DOCUMENTS</b></p> <p>X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document</p> <p>T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons &amp; : member of the same patent family, corresponding document</p>			

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0179426

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Page 2

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl. 4)
A	US-A-4 226 569 (GERARD et al.) * abstract; figure 3; claim 1 * -----		
			TECHNICAL FIELDS SEARCHED (Int. Cl. 4)
The present search report has been drawn up for all claims			
Place of search BERLIN		Date of completion of the search 20-07-1987	Examiner HYLLA W.A.
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